







The RECON-F4 is an advanced, lightweight aerial LiDAR surveying solution designed specifically for small to mid-size drones such as the DJI M400 and Freefly Astro Max. The **RECON-F4** seamlessly combines cutting-edge lightweight LiDAR technology with a high-accuracy drone optimized GNSS-INS system and an industrial-grade full-frame orthophoto camera all in a compact survey-grade 3D laser mapping solution. Combined with Phoenix LiDAR flight planning and post processing software, the RECON-F4 an efficient and cost effective solution for 3D data acquisition and processing.

FEATURES

- Weighing only 1.3 kg, the **RECON-F4** is ideal for small to mid-size drones such as the DJI M400 and Freefly Astro Max
- Integrated 45 MP full-frame calibrated orthographic RGB camera provides high resolution image mapping textures for efficient 3D model reconstruction with realistic point cloud colorization
- The powerful laser range capability combined with a wide 80° horizontal field yields a 30% - 40% increase in data acquisition efficiency over competing solutions

PAYLOAD

| OVERALL DIMENSIONS (L x W x H) | 17.5 x 11.4 x 10.3 cm |
|--------------------------------|-------------------------------|
| POWER CONSUMPTION | Up to 40 W (36 W typical) |
| WEIGHT | 1.3 kg / 2.86 lbs |
| OPERATING TEMPERATURE | -20° to +50°C (-4° to +122°F) |
| OPERATING VOLTAGE | 13.7 - 32.0 V DC |

LIDAR SENSOR

| LASER WAVELENGTH | 1535 nm (CLASS 1) | | |
|-----------------------|--|--|--|
| RANGE MIN | 5 m | | |
| RANGE MAX | 360 m at 20% reflectivity, 100 kHz PRR | | |
| PULSE REPETITION RATE | 100 to 550 kHz | | |
| SCAN SPEED | 30 - 300 lines/second | | |
| MAX RETURN COUNT | ≤7 | | |
| MIRROR TYPE | 3 facet rotating mirror | | |
| BEAM DIVERGENCE | 0.5 mrad @ 1/e | | |
| FIELD OF VIEW | 80° | | |
| LASER ACCURACY (*) | 10 mm One sigma @ 100 m | | |
| LASER PRECISION (**) | 5 mm One sigma @ 100 m | | |
| | | | |

(*) Laser accuracy is the degree of conformity of a measured quantity to its actual (true) value. (**) Laser precision is the degree to which further measurements show the same results.

CAMERA

| RESOLUTION | 45 MP | |
|--------------------|-------------------------------|--|
| FOCAL LENGTH (FOV) | 18 mm (89.84° H x 67.16° V) | |
| SENSOR SIZE | 35.9 mm x 24 mm (8184 x 5460) | |

NAVIGATION SYSTEM

| CONSTELLATION SUPPORT | GPS + GLONASS + BEIDOU + GALILEO |
|-----------------------|--|
| ACCURACY POSITION | 1 cm + 1 ppm GNSS baseline RMS horizontal |
| IMU SAMPLING RATE | 1000 Hz |
| ACCURACY ATTITUDE (5) | ROLL, PITCH: 0.005° RMS HEADING: 0.012° RMS |



QUICK SPECS

ABSOLUTE ACCURACY (1)(2)(3)

2 - 3.5 cm RMSEz @ 120 m

INTRASWATH PRECISION (1)(2)(4)

2.5 cm RMSDz @ 120 m

EXAMPLE ACQUISITIONS:

- » 120 m AGL, 6 m/s, 80° FOV, 550 kHz
- » Swath Width = 200 m
- » Avg. Density = 300 points/m²
- » Collection Rate = 4.32 km²/hr

APPLICATIONS



UTILITIES MAPPING



OIL & GAS SURVEYING RAILWAY TRACK MAPPING



CONSTRUCTION SITE SURVEYING



GENERAL MAPPING

- (1) Approximate values based on PLS test methods described at https://docs.phoenixlidar.com/accuracy-standards-and-quantification.

 (2) Using a 100° max downward field of view.

 (3) Expected RMSEz when following the PLS recommended acquisition
- & processing workflow and ASPRS check point guidelines.

 (4) Flat surfaces with >20% reflectivity at the laser's wavelength.

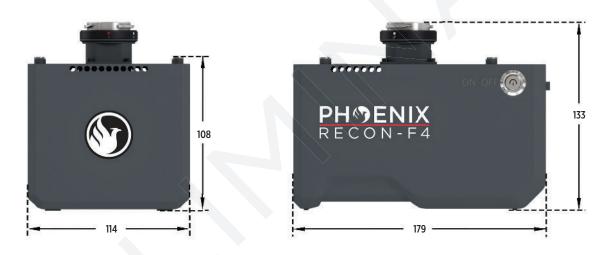
 (5) Estimated post-processed accuracy with IMU-27.

MEASUREMENT PERFORMANCE

| Laser Pulse Repetition Rate PRR 1)5) | 100 kHz | 200 kHz | 300 kHz | 400 kHz | 550 kHz | | |
|---|--------------------------------------|-------------------|-------------------|-------------------|-------------------|--|--|
| Max. Measuring Range ^{3) 4)} | ax. Measuring Range ^{3) 4)} | | | | | | |
| natural targets $P \ge 20\%$ (e.g. Dry roads) | 360 m | 330 m | 280 m | 220 m | 200 m | | |
| natural targets $P \ge 80\%$ (e.g. Limestone) | 750 m | 680 m | 500 m | 375 m | 300 m | | |
| Max. Operating Flight Altitude AGL ^{2) 5)} | | | | | | | |
| @ ρ ≥ 20% | 260 m (850 ft) | 230 m (755 ft) | 200 m (656 ft) | 160 m (525 ft) | 150 m (492 ft) | | |

¹⁾ Rounded values.

RECON-F4 DIMENSIONS (CM)



DJI M400 DRONE INTEGRATION KIT





PhoenixLiDAR.com • sales@phoenixlidar.com • USA +1.323.577.3366

¹⁾ Rounded Values.
2) Setting of intermediate PRR values possible.
3) Typical values for average conditions. Maximum range is specified for flat targets with size in excess of the laser beam diameter, perpendicular angle of incidence, and for atmospheric visibility of 23 km. In bright sunlight, the max range is shorter than under overcast sky.
4) Ambiguity to be resolved by post-processing.
5) Flat terrain assumed, scan angle +/- 40°.
6) If more than one target is hit, the total laser transmitter power is split and, accordingly, the achievable range is reduced.