



LEARN MORE



VTOL



UAV



HELICOPTER



AIRPLANE

### QUICK SPECS

#### ABSOLUTE ACCURACY <sup>(1)(2)(3)</sup>

1.5 - 3 cm RMSEz @ 120 m

#### INTRASWATH PRECISION <sup>(1)(2)(4)</sup>

2 cm RMSDz @ 120 m

#### EXAMPLE ACQUISITIONS:

##### UAV

- » 120 m AGL, 8 m/s, 100° FOV, 2400 kHz
- » Swath Width = 286 m
- » Avg. Density = 875 points/m<sup>2</sup>

##### HELICOPTER

- » 250 m AGL, 60 knots, 100° FOV, 1200 kHz
- » Swath Width = 595 m
- » Avg. Density = 54 points/m<sup>2</sup>

(1) Approximate values based on PLS test methods described at:  
<https://docs.phoenixlidar.com/accuracy-standards-and-quantification>.

(2) Using a 90° downward field of view.

(3) Expected RMSEz when following the PLS recommended acquisition & processing workflow and ASPRS check point guidelines.

(4) Flat surfaces with >20% reflectivity at the laser's wavelength.

### APPLICATIONS



UTILITIES MAPPING



RAILWAY TRACK MAPPING



CONSTRUCTION SURVEYING



AGRICULTURE & FORESTRY MONITORING



OPEN PIT MINING OPERATIONS



OIL & GAS SURVEYING

## RANGER-U160

The **RANGER-U160** adds range and density capabilities to an already unrivaled mapping system. Featuring the Riegl VUX-160<sup>23</sup> with a unique forward and rear looking field of view was designed to minimize laser shadowing and provide a high level of detail on vertical surfaces. Pulse rates up to 2400 kHz and the ability to be carried by a variety of aircraft make this a highly versatile system that is suitable for mapping at various scales in order to meet your unique project objectives. The **RANGER-U160** is ideal for corridor mapping applications such as utility, rail and pipeline inspection.

### FEATURES

- Exceptional data density with measurement rates up to 2,000,000/s
- 3 facet polygon mirror with -10° back, 0° nadir, and +10° forward for improved detail on vertical structures and surfaces
- Easily mountable to unmanned platforms (UAVs) and to helicopters, gyrocopters, and other small piloted aircrafts
- 100° lateral field of view for single pass corridor coverage

### PLATFORM

\* Without Accessories

DIMENSIONS*	27.5 x 11.7 x 22.2 cm
OPERATING VOLTAGE	20 - 28 V DC
POWER CONSUMPTION*	75 W typical
OPERATING TEMPERATURE	0° - 40° C / 32° - 104° F
WEIGHT*	3.4 kg / 7.5 lbs

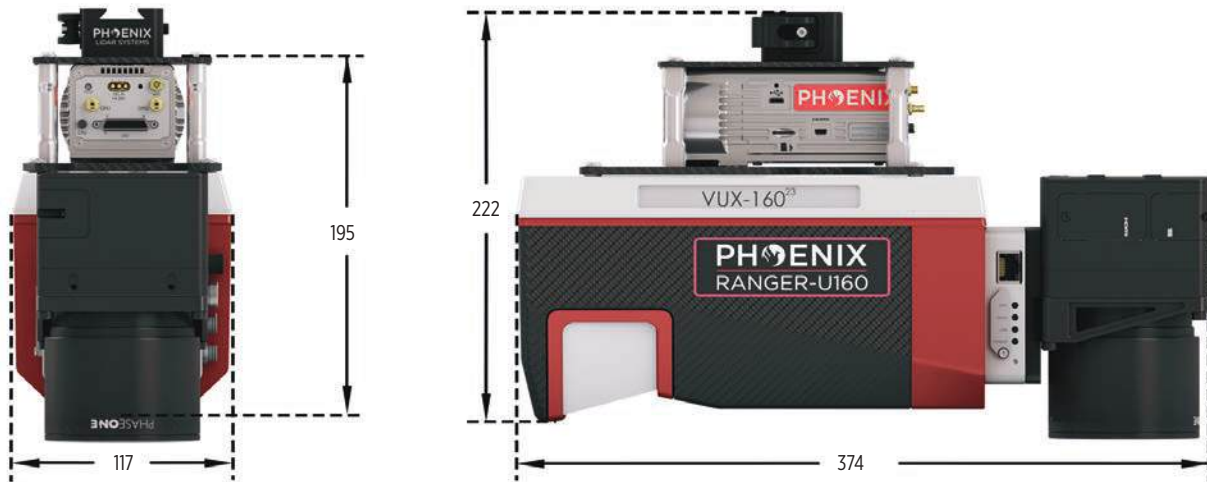
### LiDAR SENSOR

LASER WAVELENGTH	1550 nm
RANGE MINIMUM	5 m
RANGE MAXIMUM	980 m @ 20% reflectivity, 300 kHz
PULSE REPETITION RATE	300 - 2400 kHz
SCAN SPEED	50 - 400 lines/second
MAX RETURN COUNT	32
BEAM COUNT	3
BEAM DIVERGENCE	0.4 mrad
HORIZONTAL FIELD OF VIEW	100°
VERTICAL FIELD OF VIEW	20° @ nadir
LASER ACCURACY	0.01 m (1σ @ 150 m)
LASER SAFETY	CLASS 1

### NAVIGATION SYSTEM

CONSTELLATION SUPPORT	GPS + GLONASS + BEIDOU + GALILEO
SUPPORTED ALIGNMENT	Kinematic, Dual-Antenna
OPERATION MODES	Real-time, Post-Processed
ACCURACY POSITION	1 cm + 1 ppm GNSS baseline RMS Horizontal
ACCURACY ATTITUDE <sup>(5)</sup>	
ROLL, PITCH	0.002° RMS
HEADING	0.007° RMS

## RANGER-U160 DIMENSIONS (mm)



## RANGE MEASUREMENT PERFORMANCE

Laser Pulse Repetition Rate PRR <sup>1)</sup>	300 kHz	600 kHz	1200 kHz	1800 kHz	2400 kHz
<b>Max. Measuring Range <sup>2) 3)</sup></b> natural targets $\rho \geq 20\%$ natural targets $\rho \geq 60\%$ natural targets $\rho \geq 80\%$	980 m 1600 m 1800 m	720 m 1180 m 1340 m	520 m 860 m 980 m	420 m 720 m 820 m	370 m 620 m 720 m
<b>Max. Operating Flight Altitude AGL <sup>2) 4)</sup></b> @ $\rho \geq 20\%$ @ $\rho \geq 60\%$	560 m (1800 ft) 900 m (2950 ft)	400 m (1350 ft) 670 m (2200 ft)	290 m (950 ft) 490 m (1600 ft)	240 m (800 ft) 400 m (1350 ft)	210 m (700 ft) 350 m (1150 ft)
<b>Max. Number of Targets per Pulse <sup>5)</sup></b>	32	24	11	7	5

1) Rounded average PRR.

2) Typical values for average conditions and average ambient brightness. In bright sunlight, the max. range is shorter than under an overcast sky.

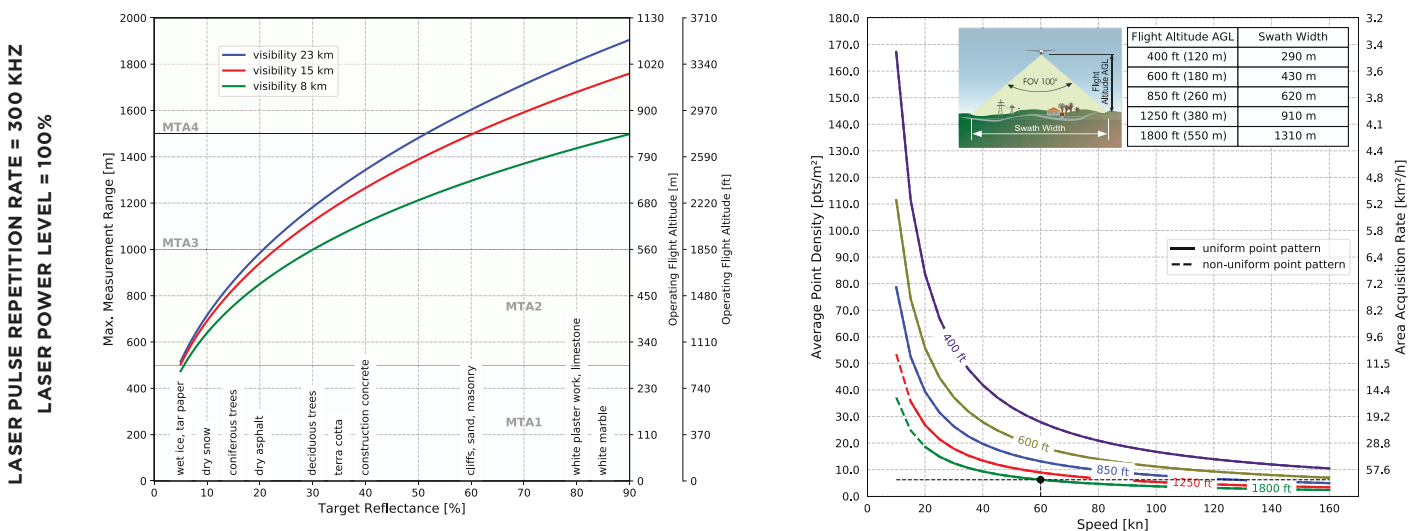
3) The maximum range is specified for flat targets with size in excess of the laser beam diameter, perpendicular angle of incidence, and for atmospheric visibility of 23 km. Range ambiguities have to be resolved by multiple-time-around processing.

4) Considering max. effective FOV 100°, additional roll angle  $\leq \pm 5$  deg.

5) If the laser beam hits, in part, more than one target, the laser's pulse power is split accordingly. Thus the achievable range is reduced.

Source: RIEGL Laser Measurement Systems

## MAX MEASUREMENT RANGE & POINT DENSITY RANGER-U160



**Example:** RANGER-U160 at 300,000 pulses/sec, laser power level 100%  
altitude 1,800 ft AGL, speed 60 km

**Results:** point density ~ 6.2 pts/m<sup>2</sup>

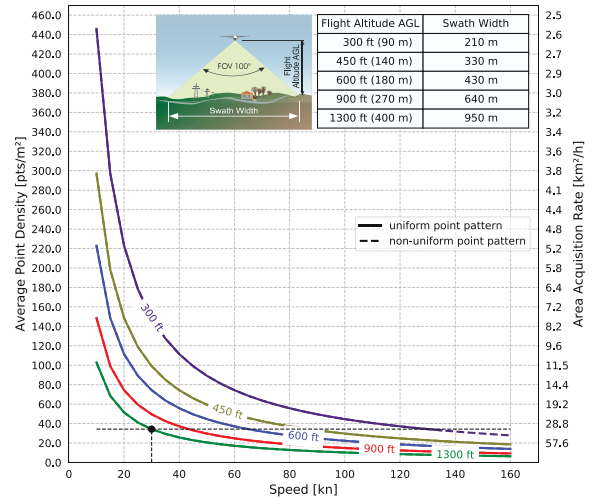
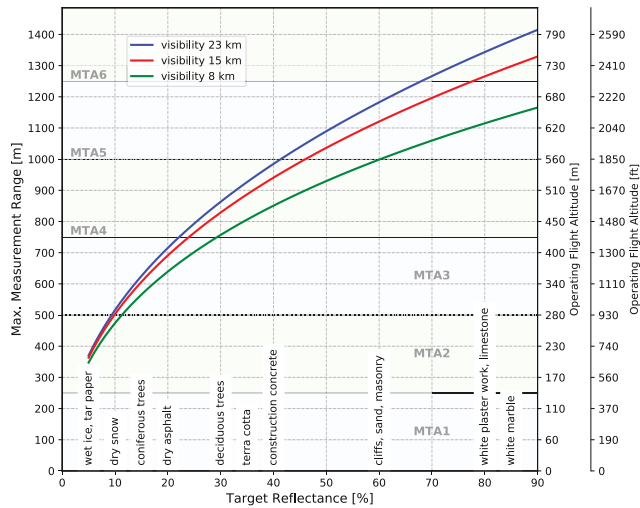
### Operating Flight Altitude AGL given for the following conditions:

- Ambiguity resolved by multiple-time-around (MTA) processing
- FOV 100°
- Average ambient brightness
- Target size  $\geq$  laser footprint
- Roll angle  $\leq \pm 5^\circ$

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# MAX MEASUREMENT RANGE & POINT DENSITY RANGER-U160

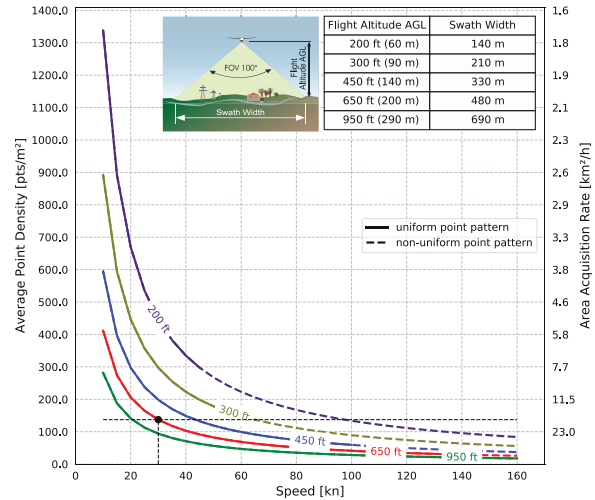
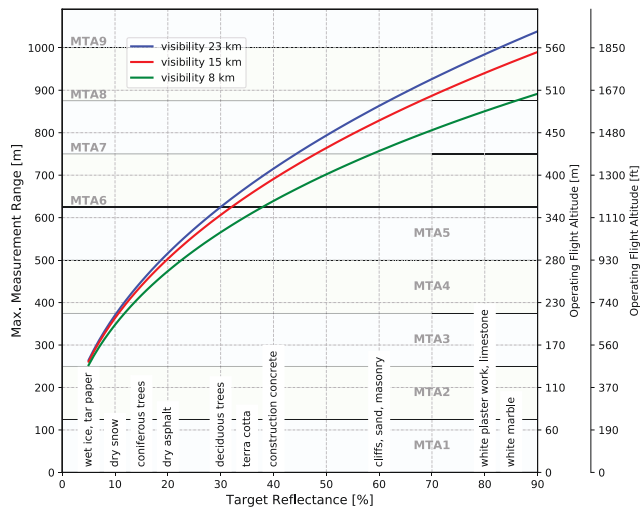
**LASER PULSE REPETITION RATE = 600 KHZ  
LASER POWER LEVEL = 100%**



**Example:** RANGER-U160 at 600,000 pulses/sec, laser power level 100%  
altitude 1,300 ft AGL, speed 30 kn

**Results:** point density - 34 pts/m<sup>2</sup>

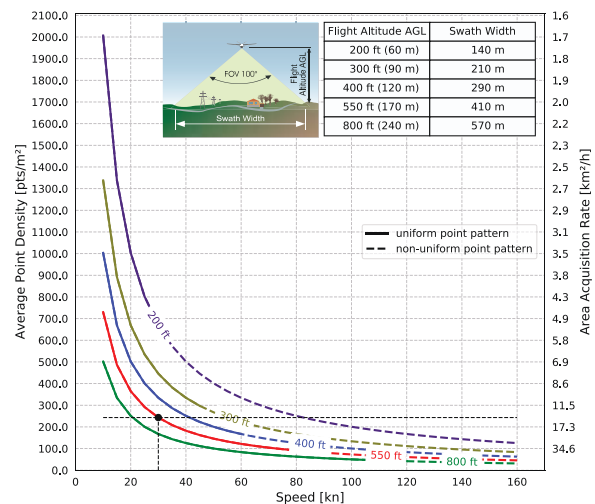
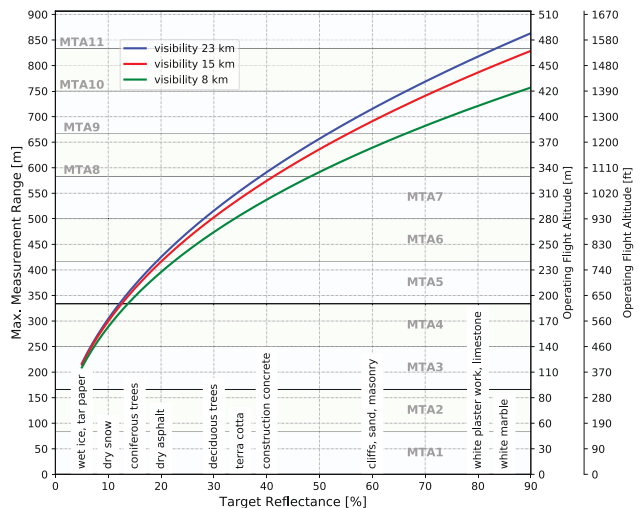
**LASER PULSE REPETITION RATE = 1200 KHZ  
LASER POWER LEVEL = 100%**



**Example:** RANGER-U160 at 1,200,000 pulses/sec, laser power level 100%  
altitude 650 ft AGL, speed 30 kn

**Results:** point density - 137 pts/m<sup>2</sup>

**LASER PULSE REPETITION RATE = 1800 KHZ  
LASER POWER LEVEL = 100%**



**Example:** RANGER-U160 at 1,800,000 pulses/sec, laser power level 100%  
altitude 550 ft AGL, speed 30 kn

**Results:** point density - 243 pts/m<sup>2</sup>

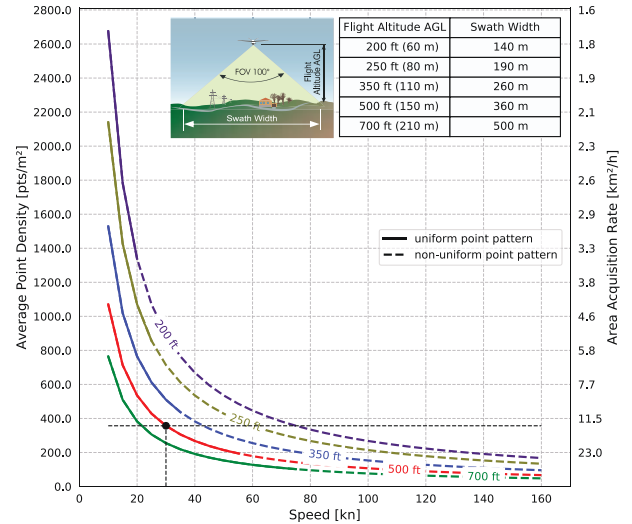
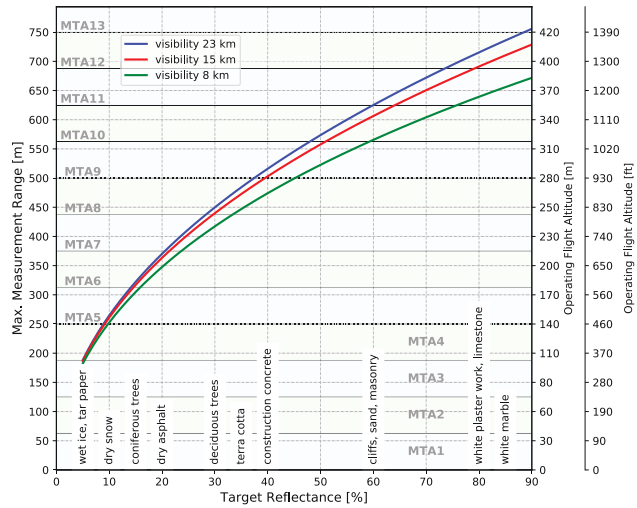
**Operating Flight Altitude AGL given for the following conditions:**

- Ambiguity resolved by multiple-time-around (MTA) processing
- FOV 100°
- Average ambient brightness
- Target size ≥ laser footprint
- Roll angle < ± 5°

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## MAX MEASUREMENT RANGE & POINT DENSITY RANGER-U160

LASER PULSE REPETITION RATE = 2400 KHZ  
LASER POWER LEVEL = 100%



**Example:** RANGER-U160 at 2,400,000 pulses/sec, laser power level 100%  
altitude 500 ft AGL, speed 30 kn

**Results:** point density - 356 pts/m<sup>2</sup>

### Operating Flight Altitude AGL given for the following conditions:

- Ambiguity resolved by multiple-time-around (MTA) processing
- FOV 100°
- Average ambient brightness
- Target size  $\geq$  laser footprint
- Roll angle  $< \pm 5^\circ$

## RANGER-U160 ACCESSORIES



R6



SONY LR1



Helicopter Mount



UltraPod



EXPLORE A PHOENIX LiDAR SYSTEM FOR YOUR TEAM, CONTACT US!

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