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VEHICLE



SLAM



UAV

QUICK SPECS

ABSOLUTE ACCURACY

2-5 cm RMSEz @ 80 m AGL ⁽¹⁾ ⁽²⁾ ⁽⁴⁾

INTRASWATH PRECISION

4.5 cm RMSDz @ 80 m AGL ⁽¹⁾ ⁽²⁾ ⁽³⁾

WEIGHT

1.8 kg / 3.9 lbs

DIMENSIONS

20.7 x 11.7 x 15.7 cm

PULSE RATE

500/1000/2000 kHz, up to 2 returns

MAX DJI M350 FLIGHT TIME

33 Minutes

APPLICATIONS



UTILITIES MAPPING



CONSTRUCTION SITE SURVEYING



AGRICULTURE & FORESTRY MONITORING



OPEN PIT MINING OPERATIONS



STOCKPILE VOLUMETRICS



GENERAL MAPPING

(1) Approximate values based on PLS test condition.

(2) Using a 90° downward field of view.

(3) Range of elevation values on flat surfaces with >20% reflectivity at the laser's wavelength.

(4) Expected RMSEz when following the PLS recommended acquisition & processing workflow and ASPRS check point guidelines.

RECON-XT/XT-A

The **Recon-XT** is the ultimate value, entry-level system for the DJI Matrice 350 and Freefly Systems Astro. A strong fit for smaller scan areas and teams on a budget. The **Recon-XT** is designed to grow and adapt with your business.

Flexibility in mounting options is a key benefit of this Phoenix system. The **Recon-XT** is designed to fly on the DJI M350 and Freefly Systems Astro (**RECON-XT-A**), and can also be adapted for vehicle and SLAM configurations.

FEATURES

- Ultralight LiDAR payload, designed for the M350 and Astro
- Flexible Mounting: Mount on a drone, vehicle, or even hand held
- Multi-Target Capacity—up to 2 target echoes per laser shot
- Fast and accurate measurement 640k shots/s, up to 1.28m points/s

PLATFORM

OVERALL DIMENSIONS	20.7 x 11.7 x 15.7 cm
PAYLOAD WEIGHT	1.8 kg / 3.9 lbs
CAMERA FOV	70°
CAMERA RESOLUTION	24 MP
EXTERNAL STORAGE	256GB USB drive included
POWER CONSUMPTION	20W typical
OPERATING VOLTAGE	12 - 28 VDC
OPERATING TEMPERATURE	-20°C - +40°C

LiDAR SENSOR

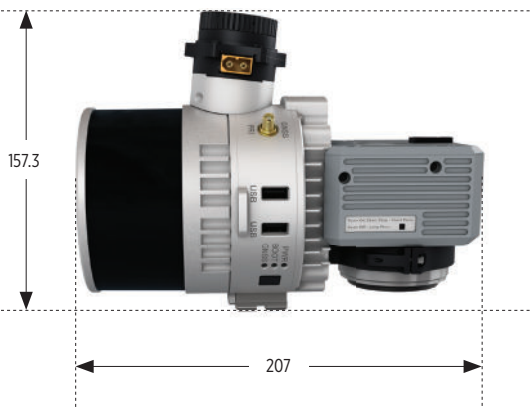
LASER PROPERTIES	905 nm Class 1 (eye safe)
RANGE MAX	120 m
RMS RANGING ERROR	10 mm (Average within 0.5 - 70 m @ 50% reflectivity)
PULSE RATE	640k points/s, up to 1.28M points/s dual return mode
FIELD OF VIEW	+15° -16° Vertical / 360° Horizontal
MULTIPLE ECHOES	2
NUMBER OF LASERS	32
BEAM DIVERGENCE	2.29 mrad / 1.52 mrad
LASER BEAM FOOTPRINT H X V	9 cm x 6 cm @ 40 m, 14 cm x 9 cm @ 60 m, 18 cm x 12 cm @ 80 m

NAVIGATION SYSTEM

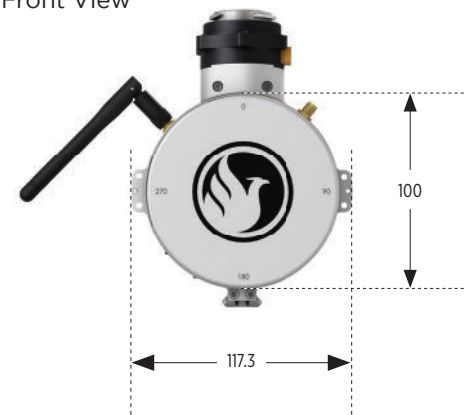
CONSTELLATION SUPPORT	GPS + GLONASS + BEIDOU + GALILEO
SUPPORT ALIGNMENT	Kinematic
OPERATION MODES	Post-processing only
POSITION ACCURACY	0.5 cm (PPK Estimated)
ATTITUDE ACCURACY	<0.01° Pitch & Roll; <0.05° Heading

RECON-Xt/ XT-A DIMENSIONS (mm)

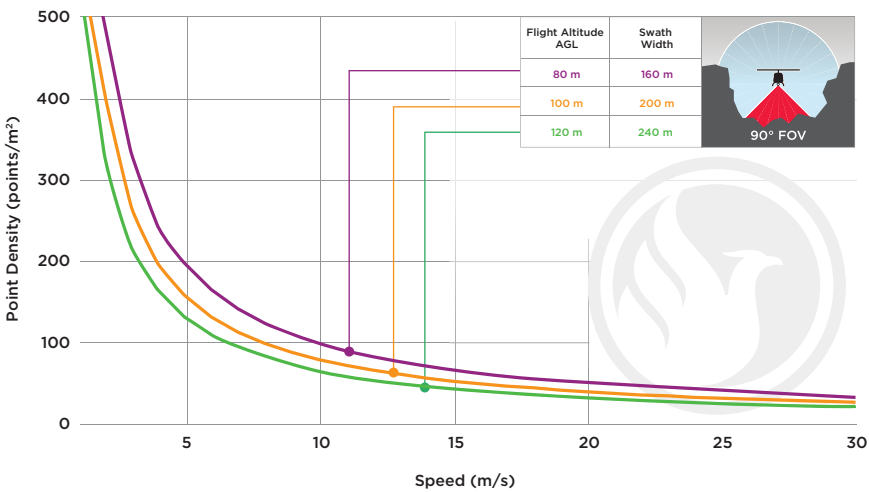
Side View



Front View



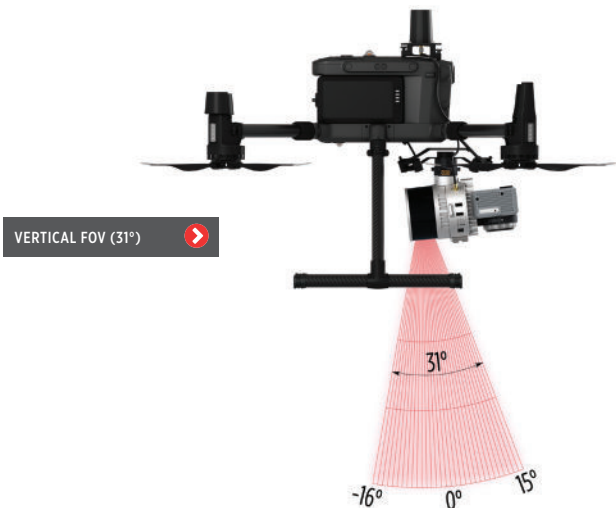
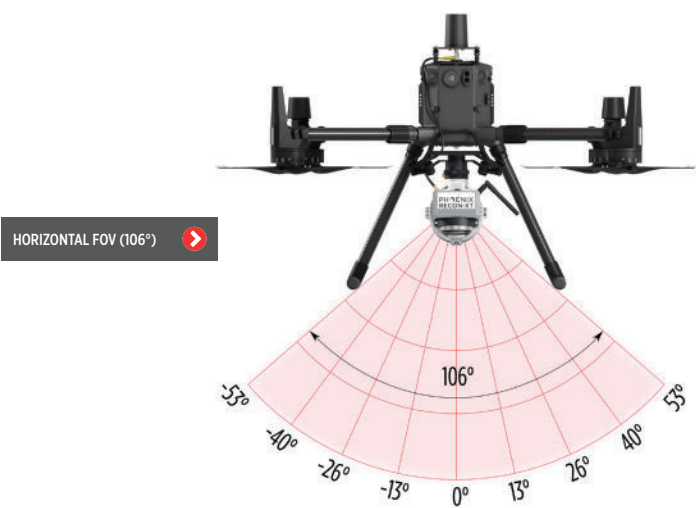
RECON-Xt/ XT-A POINT DENSITY



Flight AGL	80	100	120
Speed (m/s)	Covered Area: 20% Flightline Overlap (ha/ac)		
6	138/342	173/427	207/512
10	230/569	288/712	346/854
Speed (m/s)	Covered Area: 50% Flightline Overlap (ha/ac)		
6	86/213	108/267	130/320
10	144/356	180/445	216/534
Swath Width	160 m	200 m	240 m

1) Assuming a 30 minute flight time 2) Using a 90° downward field of view

RECON-Xt/ XT-A FIELD OF VIEW



EXPLORE A PHOENIX LiDAR SYSTEM FOR YOUR TEAM, CONTACT US!
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