













QUICK SPECS

ABSOLUTE ACCURACY (1)(2)(3)

1.5 - 3 cm RMSEz @ 120 m (preliminary)

INTRASWATH PRECISION (1)(2)(4)

1.5 cm RMSDz @ 120 m (preliminary)

EXAMPLE ACQUISITIONS:

HELICOPTER

- » 340 m AGL, 60 knots, 75° FOV, 2400 kHz
- » Swath Width = 520 m
- » Avg. Density = 124 points/m²

FIXED WING

- » 460 m AGL, 120 knots, 75° FOV, 1200 kHz
- » Swath Width = 705 m
- » Avg. Density = 23 points/m²

APPLICATIONS



UTILITIES MAPPING



RAILWAY TRACK MAPPING CONSTRUCTION SURVEYING



AGRICULTURE & FORESTRY MONITORING



OPEN PIT MINING OPERATIONS



OIL & GAS SURVEYING

GENERAL MAPPING

- (1) Approximate values based on PLS test methods described at https://docs.phoenixlidar.com/accuracystandards-and-quantification.
- (2) Using a 90° downward field of view
- (3) Expected RMSEz when following the PLS recommended acquisition & processing workflow and ASPRS check point guidelines
- (4) Flat surfaces with >20% reflectivity at the laser's wavelength.

RANGER-U240²⁴

The RANGER-U240²⁴ is a lightweight airborne laser scanner, especially designed for use on UAS and small manned airplanes or helicopters. With a wide field of view of 75 degrees and an extremely fast data acquisition rate of up to 2400 kHz, the RANGER-U24024 is perfectly suited for high point density corridor mapping applications such as power line, railway track and pipeline inspection.

FEATURES

- Easily mountable to unmanned platforms (UAVs) and to helicopters, gyrocopters, and other small manned aircrafts.
- Operating flight altitude up to 1,430 m / 4,700 ft
- Scan speed up to 600 lines/second

PLATFORM

| OVERALL DIMENSIONS (with AIR NavBox) | 34.8 x 16.4 x 18.9 cm |
|--------------------------------------|---------------------------|
| OPERATING VOLTAGE | 20 - 28 VDC |
| POWER CONSUMPTION | 85 W typical |
| OPERATING TEMPERATURE | 0° - 40° C / 32° - 104° F |
| WEIGHT (including Air NavBox) | 4.7 kg / 10.4 lbs |

LIDAR SENSOR

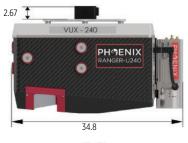
| | LASER PROPERTIES | 1550 nm | | |
|--|---|---|--|--|
| | RANGE MINIMUM | 5 m | | |
| | RANGE MAXIMUM | 1200 m @ 20% reflectivity, 300 kHz | | |
| | MAX EFFECTIVE MEASUREMENT RATE | up to 2,000,000 meas./sec | | |
| | SCAN SPEED | 40 - 600 lines/second | | |
| | LASER BEAM DIVERGENCE | 0.35 mrad | | |
| | LASER BEAM FOOTPRINT (Gaussian beam definition) | 35 mm @ 100 m, 175 mm @ 500 m, 350 mm @ 1000 m | | |
| | MAX MEASURING RANGE ρ 20% (ρ 60%) | 1200 m (1900 m) | | |
| | HORIZONTAL FIELD OF VIEW | 75° | | |
| | LASER ACCURACY | 0.01 m (1σ @ 150 m) | | |
| | LASER PRECISION | 15 mm | | |
| | LASER SAFETY | CLASS 3R ENOHD 3.5 m | | |
| | | | | |

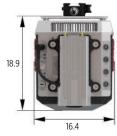
NAVIGATION SYSTEM

| CONSTELLATION SUPPORT | GPS + GLONASS + BEIDOU + GALILEO |
|--|---|
| SUPPORTED ALIGNMENT | Kinematic, Dual-Antenna |
| OPERATION MODES | Real-time, Post-Processed |
| ACCURACY POSITION | 1 cm + 1 ppm GNSS baseline RMS Horizontal |
| ACCURACY ATTITUDE ⁽⁵⁾ ROLL, PITCH HEADING | 0.002° RMS 0.007° RMS |

RANGER-U240²⁴ DIMENSIONS (cm)

RANGE MEASUREMENT PERFORMANCE

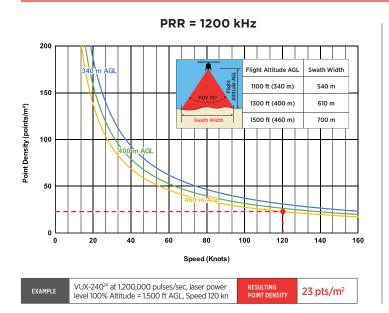


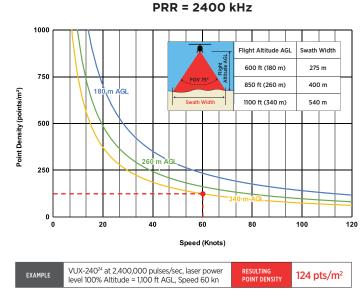


| Laser Pulse Repetition Rate PRR ¹⁾ | 300 kHz | 600 kHz | 1200 kHz | 1800 kHz | 2400 kHz |
|---|-----------|-----------|-----------|-----------|-----------|
| Max. Measuring Range ^{2) 3)} natural targets $\rho \ge 20\%$ natural targets $\rho \ge 60\%$ | 1200 m | 880 m | 640 m | 530 m | 460 m |
| | 1940 m | 1440 m | 1060 m | 880 m | 770 m |
| Max. Operating Flight Altitude AGL ^{2) 4)} $@ \rho \ge 20\%$ $@ \rho \ge 60\%$ | 890 m | 650 m | 470 m | 390 m | 340 m |
| | (2900 ft) | (2150 ft) | (1550 ft) | (1250 ft) | (1100 ft) |
| | 1430 m | 1060 m | 780 m | 650 m | 570 m |
| | (4700 ft) | (3500 ft) | (2550 ft) | (2150 ft) | (1850 ft) |
| Max. Number of Targets per Pulse 5) | 30 | 24 | 11 | 7 | 5 |

- 1) Rounded average PRR
- 2) Typical values for average conditions and average ambient brightness. In bright sunlight, the max. range is shorter than under an overcast sky.
- 3) The maximum range is specified for flat targets with size in excess of the laser beam diameter, perpendicular angle of incidence, and for atmospheric visibility of 23 km. Range ambiguities have to be resolved by multiple-time-around processing.
- 4) Effective FOV 75°, additional roll angle ± 5°.
- 5) If the laser beam hits, in part, more than one target, the laser's pulse power is split accordingly. Thus the achievable range is reduced.

MAX MEASUREMENT RANGE & POINT DENSITY RANGER-U240²⁴





RANGER-U240²⁴ ACCESSORIES









EXPLORE A PHOENIX LIDAR SYSTEM FOR YOUR TEAM, CONTACT US!

PhoenixLiDAR.com • sales@phoenixlidar.com • USA +1.323.577.3366